

# Fundamentals of Statistical Learning Theory

INSIDE-HEART Spring School – AI

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UNIVERSITÀ  
DEGLI STUDI  
DI MILANO

# Statistical Learning Theory

In the words of Vapnik:<sup>1</sup>

- *“...theoretical analysis of the problem of function estimation from a given collection of data...”*
- *“...a tool for creating practical algorithms for estimating multidimensional functions.”*

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<sup>1</sup>Vladimir Vapnik (1999). “An overview of statistical learning theory”. In: *IEEE Trans. Neural Networks* 10.5, pp. 988–999.

# The Problems of Machine Learning...

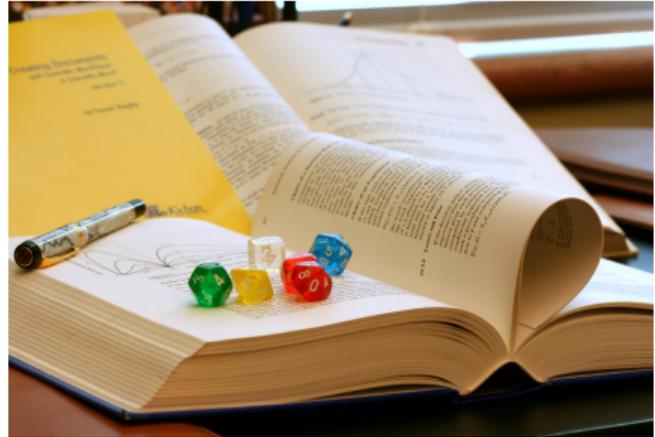
- **Classification**
- Regression
- Clustering
- Prediction
- Decision-making
- ...



## ...Under the Lens of Probability Theory

Assumptions on the *distribution* of data

- Independence
- Stationarity
- ...



## Some Important Questions

- What are the theoretical limits of a learning algorithm?
- How much data do I need?
- What is a good model?
- *Why do I need a test set?*

▶ The Learning Problem

▶ Bias-Variance Tradeoff

▶ PAC Learning

▶ VC Theory

## (Supervised) Learning Problem

- $\mathcal{X}$ : input space
- $\mathcal{Y}$ : target space
- $\mathcal{D}$ : data distribution over  $\mathcal{X} \times \mathcal{Y}$
- $\ell : \mathcal{Y} \times \mathcal{Y} \rightarrow [0, +\infty)$ : loss function

## Example: Binary Classification

- $\mathcal{X} \subseteq \mathbb{R}^d$ : samples identified by their *features*
- $\mathcal{Y} = \{0, 1\}$ : negative or positive class
- $\mathcal{D}$ : distribution of samples with their *true* labels (unknown)
- Zero-one loss

$$\ell(\gamma, \hat{\gamma}) = \begin{cases} 0 & \text{if } \hat{\gamma} = \gamma \\ 1 & \text{otherwise} \end{cases}$$



## Example: Single-Output Regression

- $\mathcal{X} \subseteq \mathbb{R}^d$ : samples identified by their *features*
- $\mathcal{Y} = \mathbb{R}$ : numerical measurement
- $\mathcal{D}$ : distribution of samples with their measurements
- Quadratic loss:  $\ell(y, \hat{y}) = (y - \hat{y})^2$



## Data and Datasets

The fundamental assumption on **data**:

$$(X, Y) \sim \mathcal{D} \quad \text{i.i.d.}$$

A **dataset** is formed by sampling  $(X_i, Y_i) \sim \mathcal{D}$  *independently* for  $i = 1, \dots, n$

$$S = \{(X_1, Y_1), (X_2, Y_2), \dots, (X_n, Y_n)\}$$

I will write  $S \sim \mathcal{D}^n$

# Predictors

A **predictor** is a function

$$h : \mathcal{X} \rightarrow \mathcal{Y}$$

Examples:

- Classifier:  $h : \mathbb{R}^d \rightarrow \{0, 1\}$
- Regressor:  $h : \mathbb{R}^d \rightarrow \mathbb{R}$

# Statistical Risk

A *good* predictor has small **Statistical Risk** (a.k.a. Population Risk a.k.a. Expected Loss)

$$\mathcal{L}(h) = \mathbb{E}[\ell(h(X), Y)]$$

where  $(X, Y) \sim \mathcal{D}$

It's the expected loss of a “test” sample

## Bayes Optimal Predictor

$$h^*(x) = \arg \min_{\hat{y} \in \mathcal{Y}} \mathbb{E}[\ell(\hat{y}, Y) | X = x]$$

Bayes risk:  $\mathcal{L}(h^*)$  (typically *larger* than zero)

### Theorem

$$\mathcal{L}(h^*) \leq \mathcal{L}(h) \text{ for every predictor } h$$

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To compute the Bayes optimal predictor you need to know  $\mathcal{D}$

## Bayes Optimal Predictor: Examples (1/2)

**Binary Classification:** let  $p(x) = \mathbb{P}(Y = 1|X = x)$

$$h^*(x) = \begin{cases} 0 & \text{if } p(x) < 1/2 \\ 1 & \text{otherwise} \end{cases}$$

Bayes risk:  $\mathcal{L}(h^*) = \mathbb{E}[\min\{p(X), 1 - p(X)\}]$

Bayes risk is **zero** if labels are assigned deterministically

## Bayes Optimal Predictor: Examples (2/2)

Regression:

$$h^*(\mathbf{x}) = \mathbb{E}[Y|X = \mathbf{x}]$$

Bayes risk:  $\mathcal{L}(h^*) = \mathbb{E}[\text{Var}[Y|X]]$

## Bayes Optimal Predictor: Examples (2/2)

Regression:

$$h^*(\mathbf{x}) = \mathbb{E}[Y|X = \mathbf{x}]$$

Bayes risk:  $\mathcal{L}(h^*) = \mathbb{E}[\text{Var}[Y|X]]$

*Gaussian model:*  $Y = f(X) + \eta$ ,  $\eta \sim \mathcal{N}(0; \sigma^2)$  i.i.d.

$$h^*(\mathbf{x}) = f(\mathbf{x})$$

Bayes risk:  $\mathcal{L}(h^*(\mathbf{x})) = \sigma^2$

# Empirical Risk

a.k.a. Average Loss

Given i.i.d. dataset  $S = \{(X_1, Y_1), \dots, (X_n, Y_n)\}$

$$\mathcal{L}_S(h) = \frac{1}{n} \sum_{i=1}^n \ell(h(X_i), Y_i)$$

- Binary classification:  $\mathcal{L}_S(h)$  = ratio of incorrect classifications
- Regression:  $\mathcal{L}_S(h)$  = Mean Squared Error (MSE)

## Theorem

For a **fixed**  $h$  (independent of  $S$ ),  $\mathbb{E}[\mathcal{L}_S(h)] = \mathcal{L}(h)$

▶ The Learning Problem

▶ Bias-Variance Tradeoff

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## Hypothesis Classes

Let  $\mathcal{S}$  be the set of all possible datasets,  $\mathcal{F}$  be the set of all functions  $\mathcal{X} \rightarrow \mathcal{Y}$

A **hypothesis class** is a set of predictors

$$\mathcal{H} \subseteq \mathcal{F}$$

A **learning algorithm** maps *datasets* to *predictors*

$$A : \mathcal{S} \rightarrow \mathcal{F}$$

A learning algorithm (implicitly) defines a hypothesis class

$$\mathcal{H} = \{A(S) \mid S \in \mathcal{S}\}$$

# No-Free-Lunch Theorem

Consider *binary classification* with the zero-one loss

## Theorem

Let  $n < |\mathcal{X}|/2$ . For every learning algorithm  $A$ , there exists a data distribution  $\mathcal{D}$  such that

1. There exists a predictor  $h^*$  such that  $\mathcal{L}(h^*) = 0$
2.  $\mathbb{P}(\mathcal{L}(A(S)) \geq 1/8) \geq 1/7$

where  $S \sim \mathcal{D}^n$

# No-Free-Lunch Theorem's Lesson

*There is no universal learner*

- For every learner, there exists a task on which it fails
- We need prior knowledge about the **specific** task at hand
- Equivalent to restricting the hypothesis class  $\mathcal{H}$



Figure 1: Not what we do

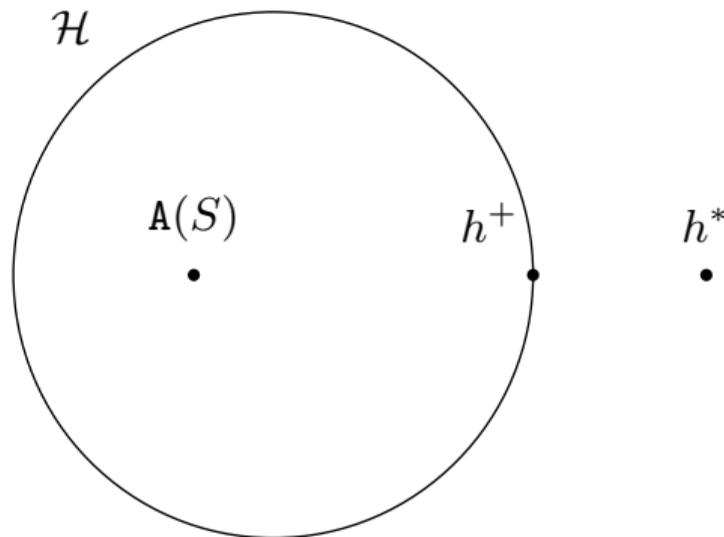
# Bias-Variance Decomposition

Fix a learning problem  $(\mathcal{X}, \mathcal{Y}, \mathcal{D}, \ell)$  and an algorithm  $A$  with hypothesis class  $\mathcal{H}$

- Let  $h^+$  be the best predictor in  $\mathcal{H}$

$$h^+ \in \arg \min_{h \in \mathcal{H}} \mathcal{L}(h)$$

- By definition  $A(S) \in \mathcal{H}$
- Bayes optimal predictor  $h^*$  may not belong to  $\mathcal{H}$



# Bias-Variance Decomposition

$$\mathcal{L}(A(S)) = \mathcal{L}(A(S)) - \mathcal{L}(h^+)$$

**variance**

$$+ \mathcal{L}(h^+) - \mathcal{L}(h^*)$$

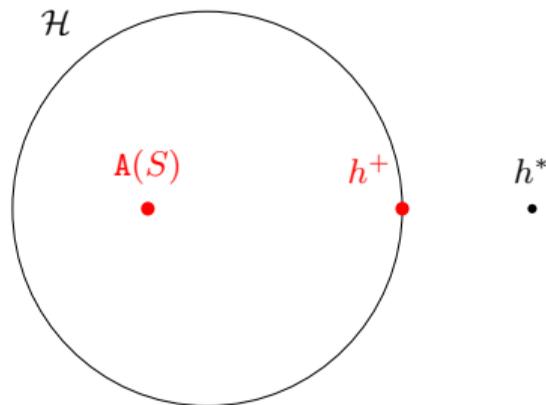
**bias**

$$+ \mathcal{L}(h^*)$$

Bayes risk (irreducible)

## Variance or Estimation Error

$$\mathcal{L}(A(S)) - \mathcal{L}(h^+)$$



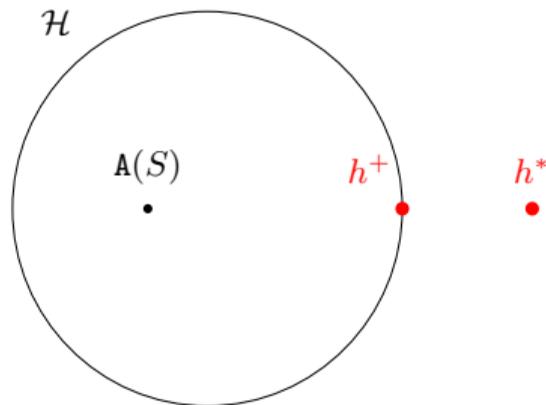
*Large estimation error*

$\implies$   $S$  is not informative enough to identify  $h^+$  within  $\mathcal{H}$

$\implies$  **overfitting**

## Bias or Approximation Error

$$\mathcal{L}(h^+) - \mathcal{L}(h^*)$$



*Large approximation error*

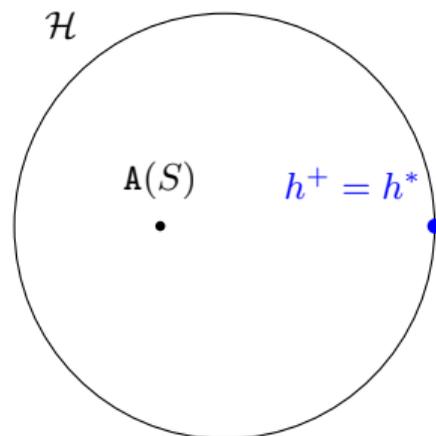
$\implies \mathcal{H}$  does not contain a good approximation of  $h^*$

$\implies$  **underfitting**

# Realizability

If  $\mathcal{H}$  contains the Bayes optimal predictor

$$h^+ = h^* \implies \mathcal{L}(h^+) - \mathcal{L}(h^*) = 0$$



**No approximation error**

▶ The Learning Problem

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# The Importance of Statistical Risk

- If **empirical risk**  $\mathcal{L}_S(A(S))$  is large, we are *underfitting* ( $\mathcal{H}$  is too small)
- Even if  $\mathcal{L}_S(A(S))$  is small, we may be *overfitting* the training set  $S$
- How would  $A(S)$  perform on a test sample  $(X, Y) \sim \mathcal{D}$ ?
- This is measured by **statistical risk**  $\mathcal{L}(A(S))$

## Measuring the Statistical Risk with a Test Set

Let  $Q = \{(X'_1, Y'_1), \dots, (X'_m, Y'_m)\}$  be a **test set** of size  $m$  independent of  $S$

**Test error:**

$$\mathcal{L}_Q(h) = \frac{1}{m} \sum_{i=1}^m \ell(h(X'_i), Y'_i)$$

### Theorem

The test error is an unbiased estimate of the statistical risk of  $A(S)$ :

$$\mathbb{E}[\mathcal{L}_Q(A(S)) \mid S] = \mathcal{L}(A(S))$$

# Upper-Bounding the Statistical Risk with the Test Error

Pick a *failure probability*  $\delta \in (0, 1)$

## Theorem

With probability  $1 - \delta$

$$\mathcal{L}(A(S)) \leq \mathcal{L}_Q(A(S)) + \sqrt{\frac{1}{2m} \log \frac{1}{\delta}}$$

## Measuring the Statistical Risk without a Test Set

- All we have is **training error**  $\mathcal{L}_S(A(S))$
- $\mathcal{L}_S(A(S))$  is **not** an unbiased estimate of the statistical risk!
- $A(S)$  computed and evaluated on the same data  $S \rightarrow$  loss **underestimation**
- It's a problem of *statistical dependence*

# Upper Bounding the Statistical Risk with the Training Error

Consider a *finite* hypothesis class  $\mathcal{H}$

## Theorem (Generalization Bound)

With probability  $1 - \delta$

$$\mathcal{L}(A(S)) \leq \mathcal{L}_S(A(S)) + \sqrt{\frac{1}{2n} \log \frac{|\mathcal{H}|}{\delta}}$$

Larger hypothesis class  $\implies$  I can trust empirical risk less (more prone to overfitting)

# Empirical Risk Minimization (ERM) Algorithm

Given hypothesis class  $\mathcal{H}$

$$\text{ERM}(S) \in \arg \min_{h \in \mathcal{H}} \mathcal{L}_S(h)$$

- ERM minimizes the training loss
- It reflects the practice of fitting function approximators on training data
- Implementation can vary greatly depending on  $\mathcal{H}$
- Minimization can be inexact in practice

# PAC Bound

Probably Approximately Correct

## PAC bound for ERM

With probability  $1 - \delta$

$$\mathcal{L}(\text{ERM}(S)) \leq \min_{h \in \mathcal{H}} \mathcal{L}(h) + \epsilon$$

where

$$\epsilon = \sqrt{\frac{2}{n} \log \frac{2|\mathcal{H}|}{\delta}}$$

ERM is *probably* ( $1 - \delta$ ) *approximately* ( $\epsilon$ ) correct

## PAC Learnability

Hypothesis class  $\mathcal{H}$  is **PAC-learnable** if it admits a learning algorithm  $A$  and a **sample complexity**  $n_{\epsilon, \delta}$  with the following property:

*For every  $\mathcal{D}$  and every  $\epsilon > 0, \delta \in (0, 1)$ , with probability  $1 - \delta$  over datasets  $S$  of size  $n \geq n_{\epsilon, \delta}$*

$$\mathcal{L}(A(S)) \leq \min_{h \in \mathcal{H}} \mathcal{L}(h) + \epsilon$$

# PAC Learnability of Finite Classes

A simple consequence of the ERM PAC bound

## Theorem

Finite hypothesis classes are PAC learnable with sample complexity

$$n_{\epsilon, \delta} = \frac{1}{2\epsilon^2} \log \frac{2|\mathcal{H}|}{\delta}$$

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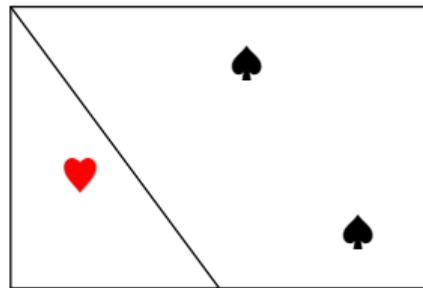
## Linear Classifier

Let  $\mathcal{X} = \mathbb{R}^2$ ,  $\mathcal{Y} = \{\spadesuit, \heartsuit\}$  and

$$\mathcal{H} = \{h_{a,b} \mid a, b \in \mathbb{R}\}$$

where

$$h_{a,b}(x) = \begin{cases} \spadesuit & \text{if } a^\top x + b < 0 \\ \heartsuit & \text{otherwise} \end{cases}$$



$$|\mathcal{H}| = |\mathbb{R}^2| = \infty$$

## Infinite Hypothesis Classes

If  $|\mathcal{H}| = \infty$ , PAC bounds become *vacuous*

$$\epsilon = \sqrt{\frac{2}{n} \log \frac{2|\mathcal{H}|}{\delta}} = \infty$$

We need a different **measure of complexity** for  $\mathcal{H}$

# VC Dimension

Vapnik-Chervonenkis Dimension<sup>2</sup>

Consider binary classification with the zero-one loss

Hypothesis class  $\mathcal{H}$  **shatters** finite set  $E \subseteq \mathcal{X}$  if, for any binary labeling of the elements of  $E$ , there is  $h \in \mathcal{H}$  that perfectly classifies them

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<sup>2</sup>V. N. Vapnik and A. Ya. Chervonenkis (1971). "On the Uniform Convergence of Relative Frequencies of Events to Their Probabilities". In: *Theory of Probability & Its Applications* 16.2, pp. 264–280.

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$VC(\mathcal{H})$  is the cardinality of the largest set that can be shattered by  $\mathcal{H}$

If this is unbounded,  $VC(\mathcal{H}) = \infty$

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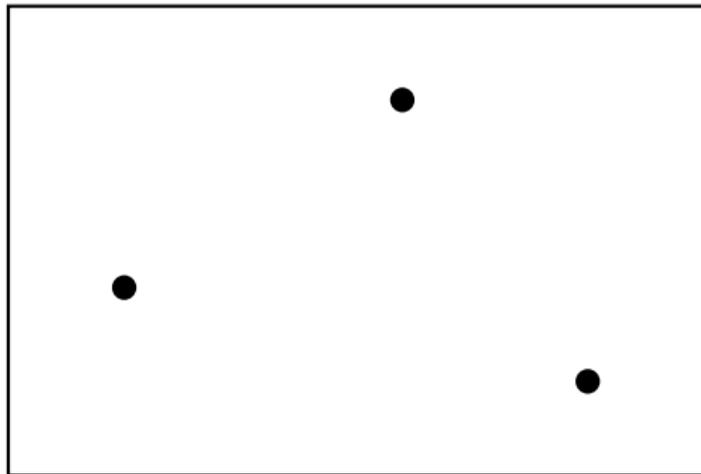
## VC Dimension of Linear Classifiers in $\mathbb{R}^2$ (Lower Bound)

There is *at least one* set of 3 points that is shattered by  $\mathcal{H} \implies \text{VC}(\mathcal{H}) \geq 3$



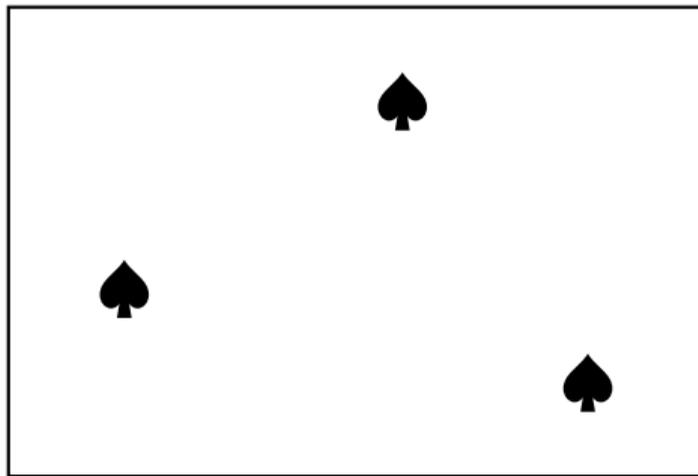
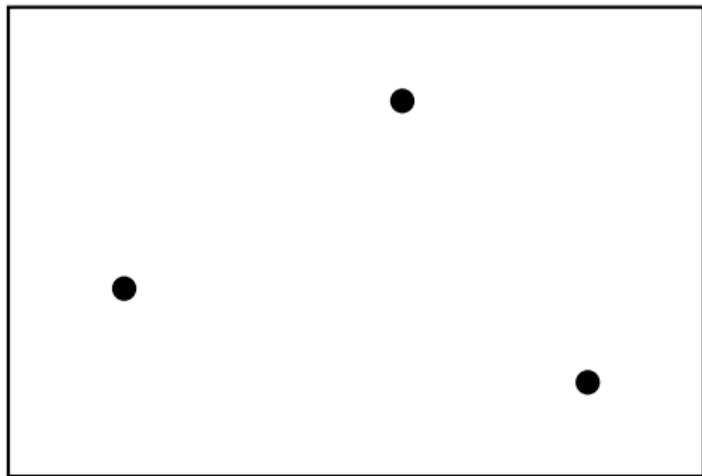
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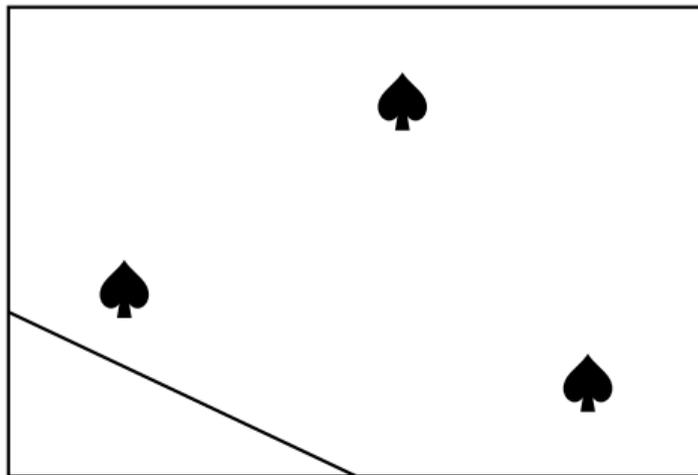
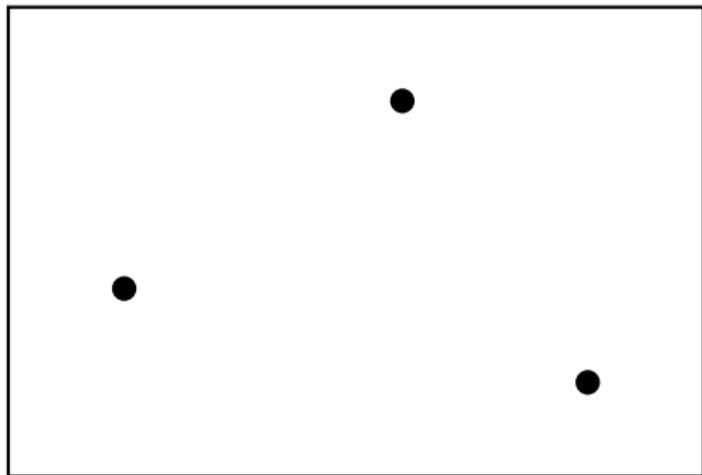
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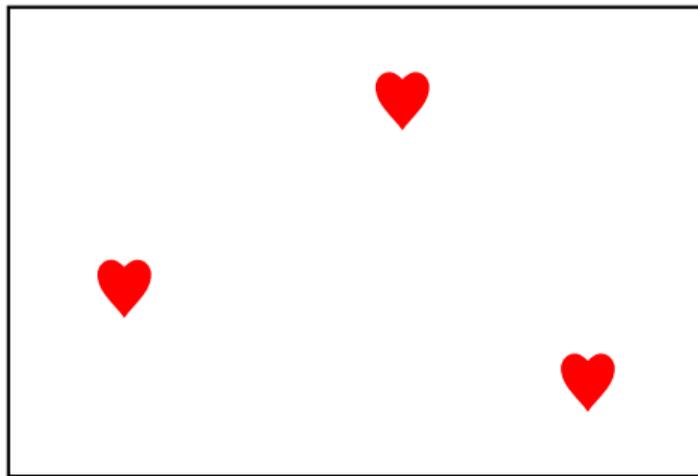
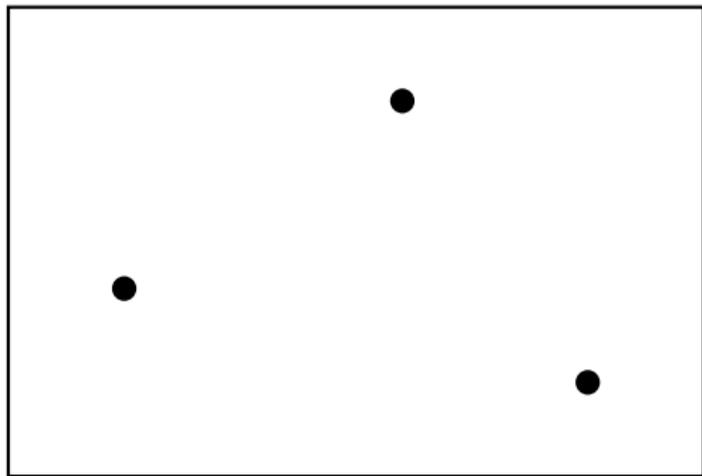
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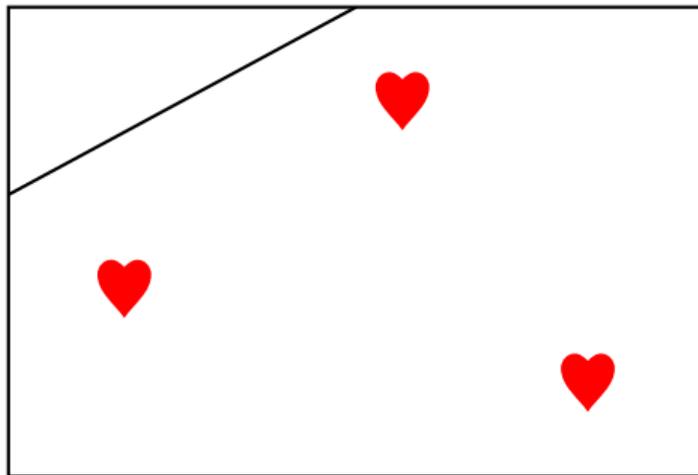
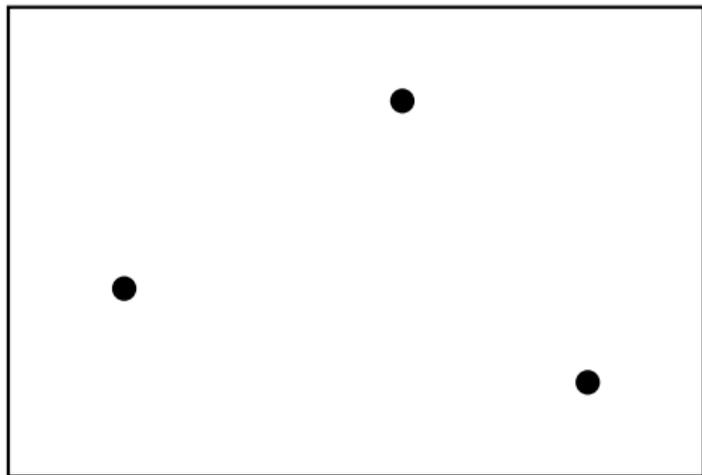
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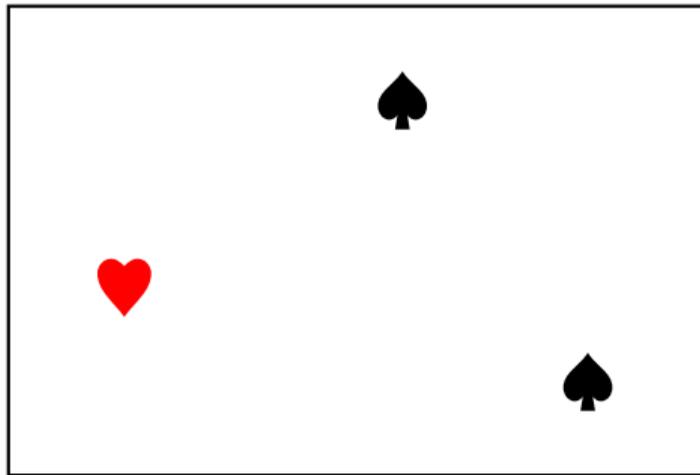
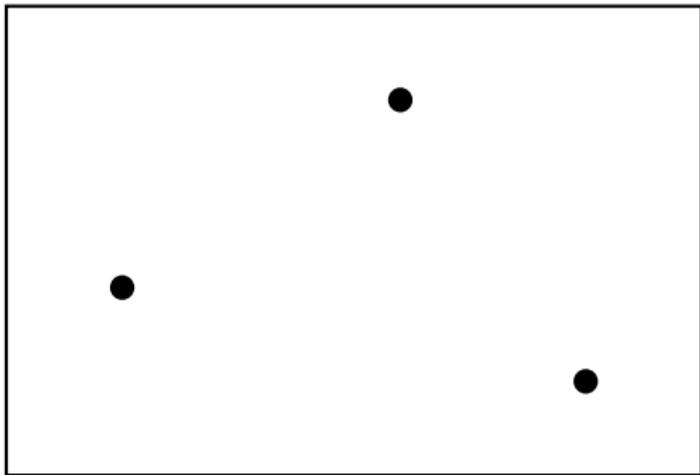
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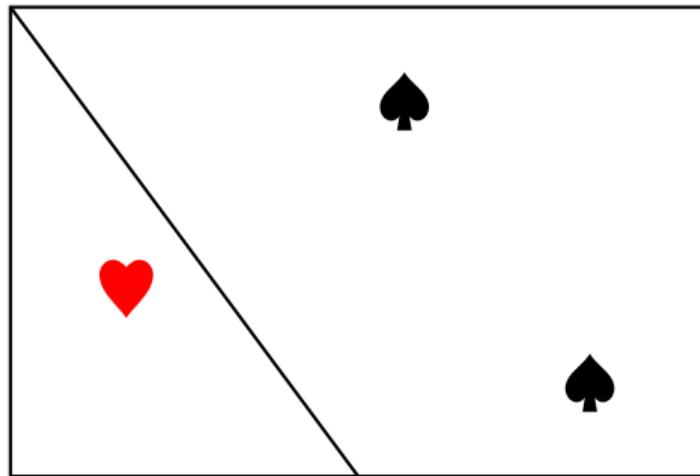
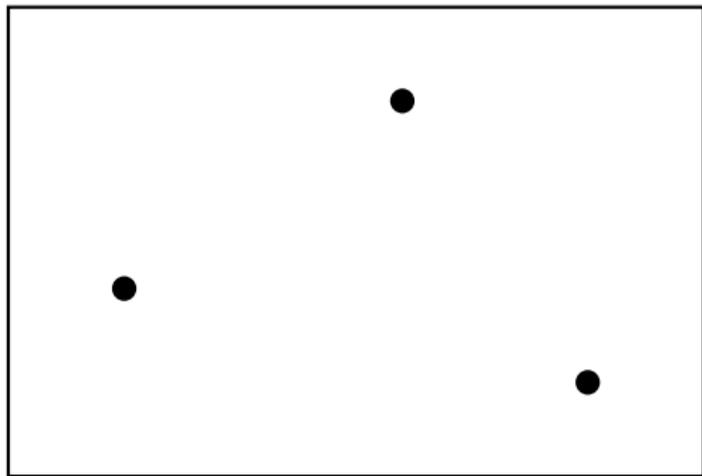
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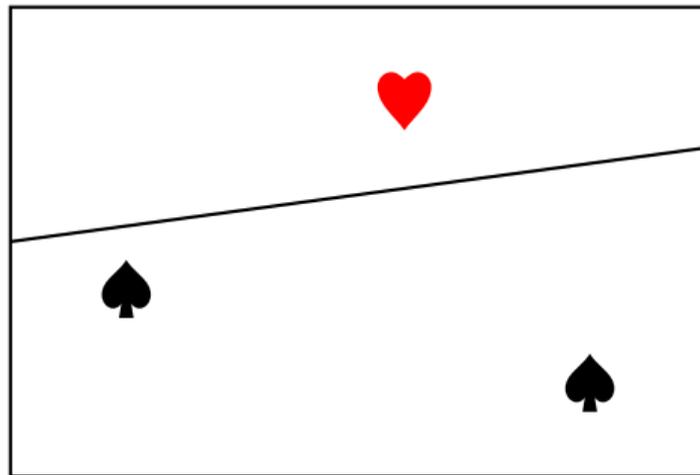
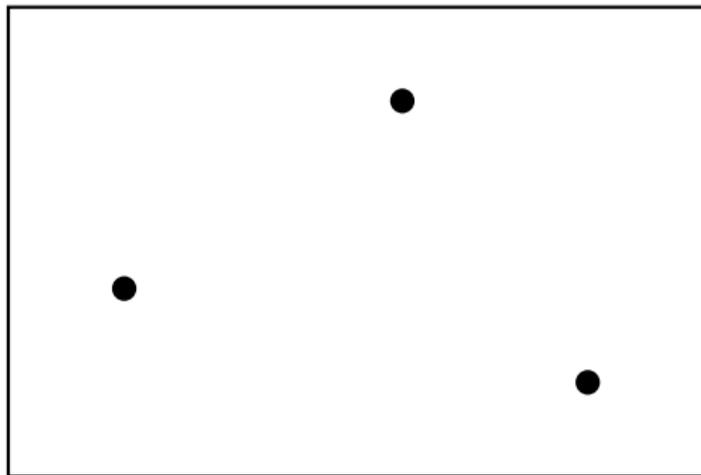
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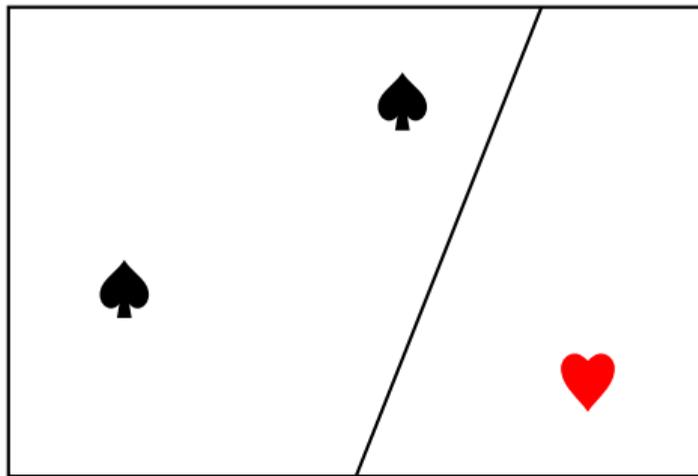
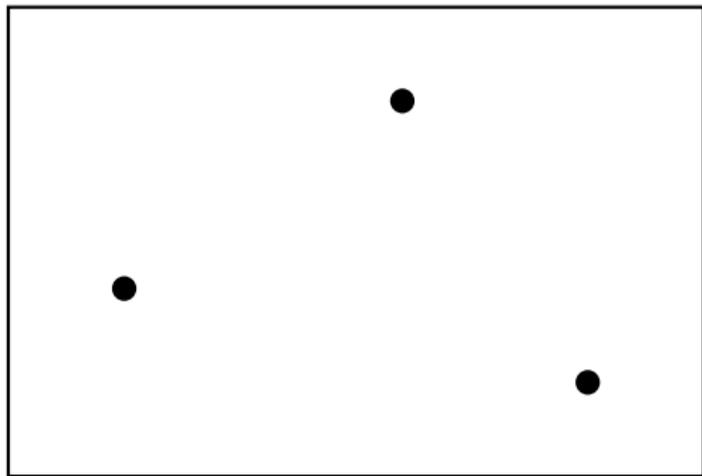
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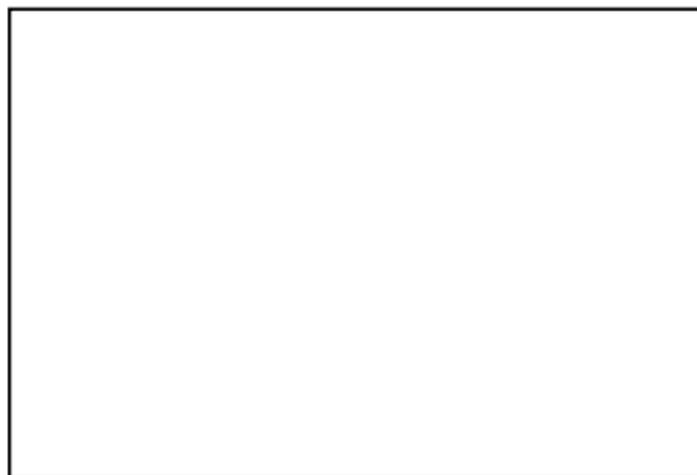
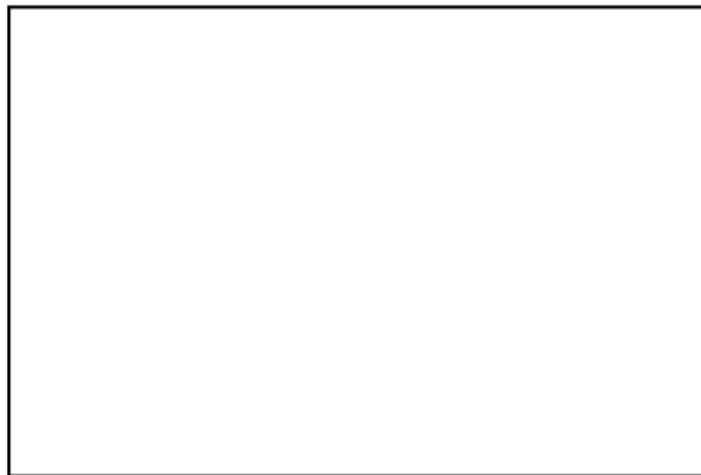
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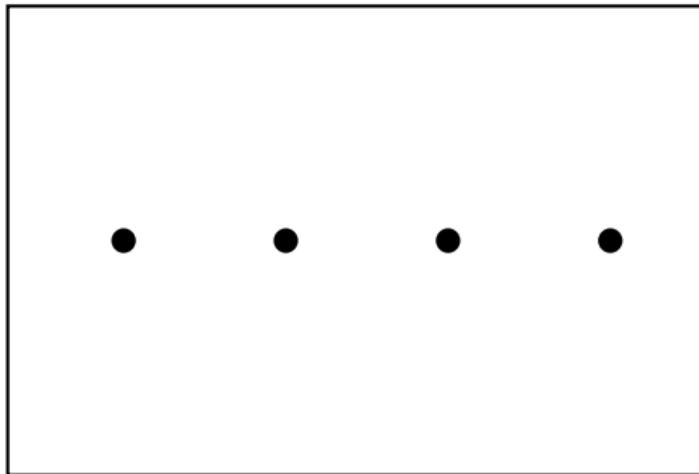
## VC Dimension of Linear Classifiers in $\mathbb{R}^2$ (Upper Bound)

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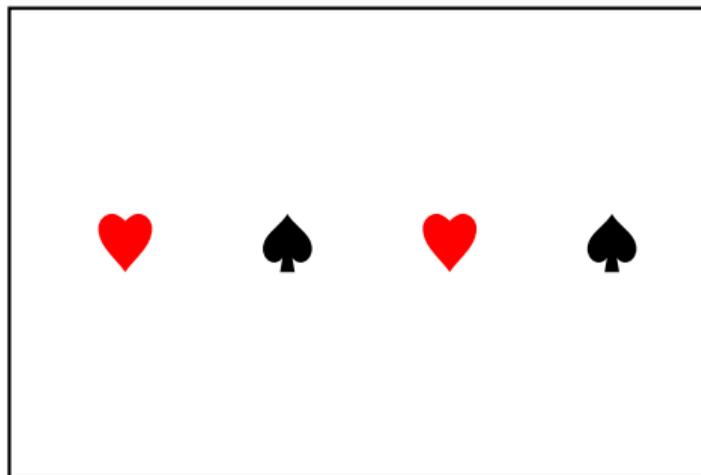
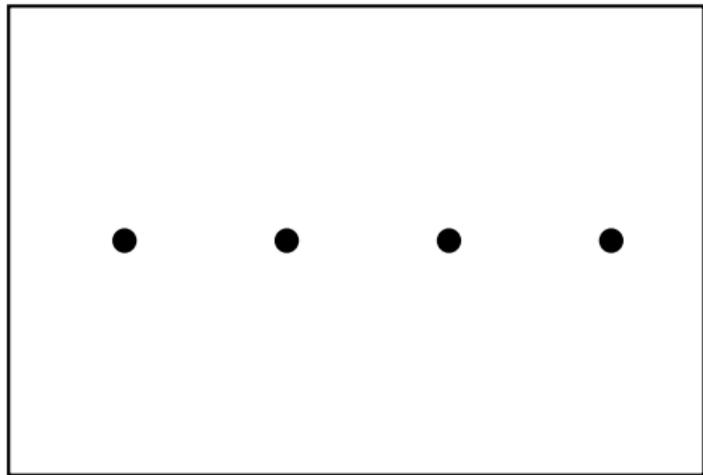
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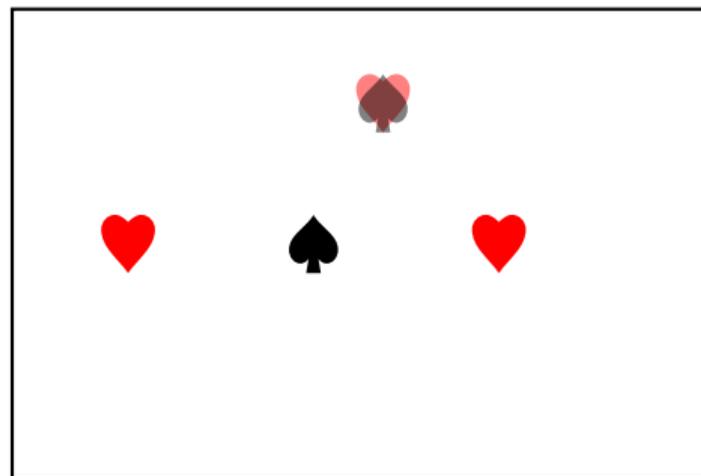
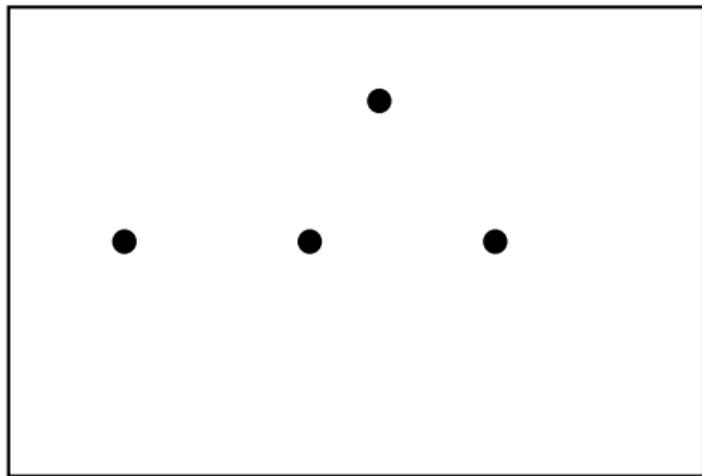
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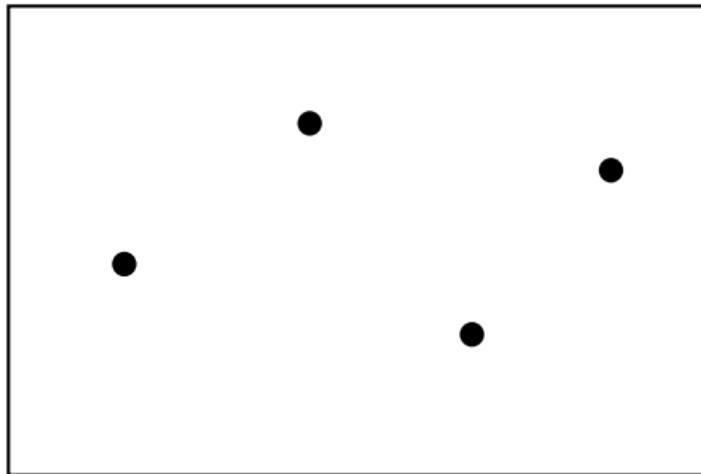
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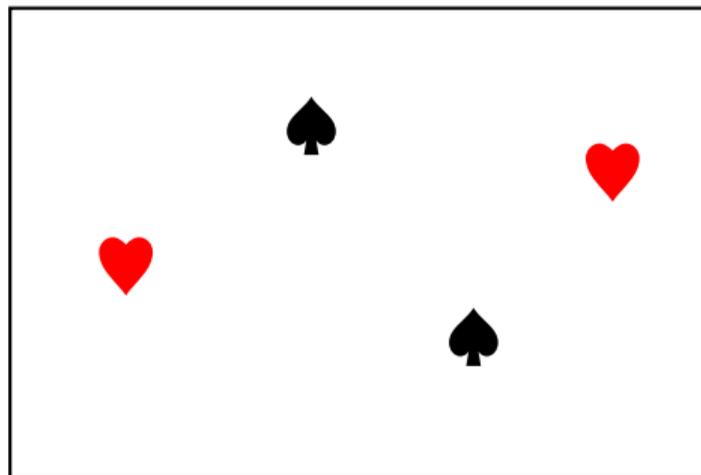
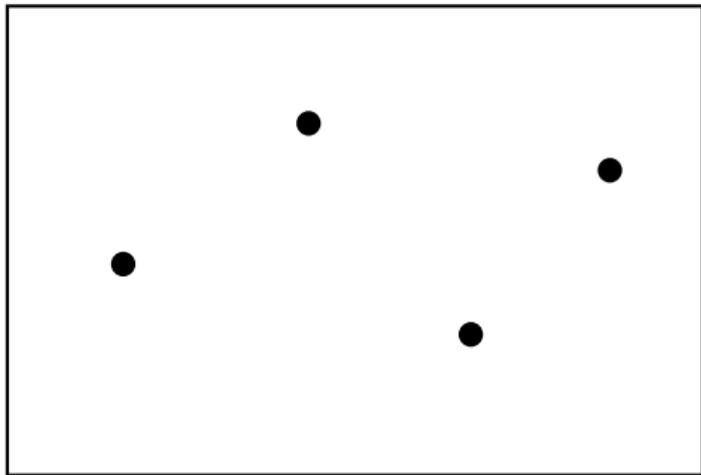
## VC Dimension of Linear Classifiers in $\mathbb{R}^2$ (Upper Bound)

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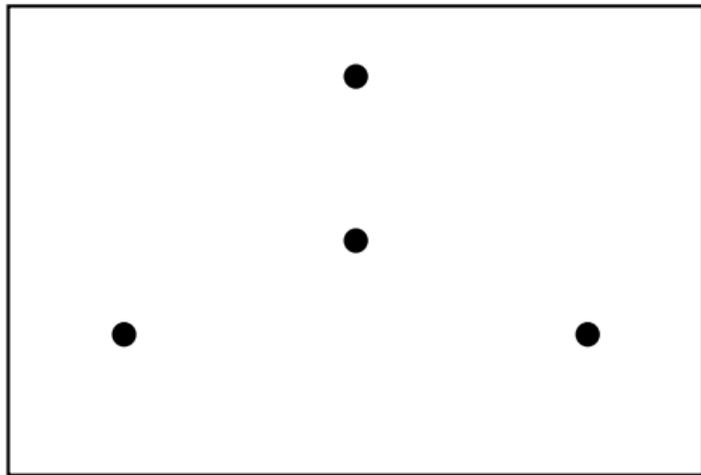
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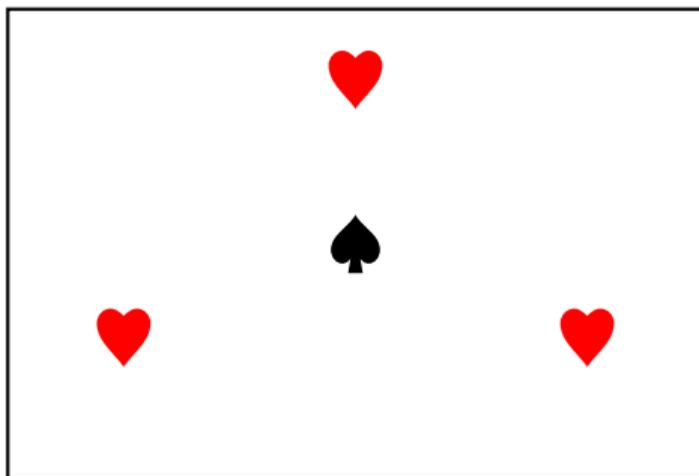
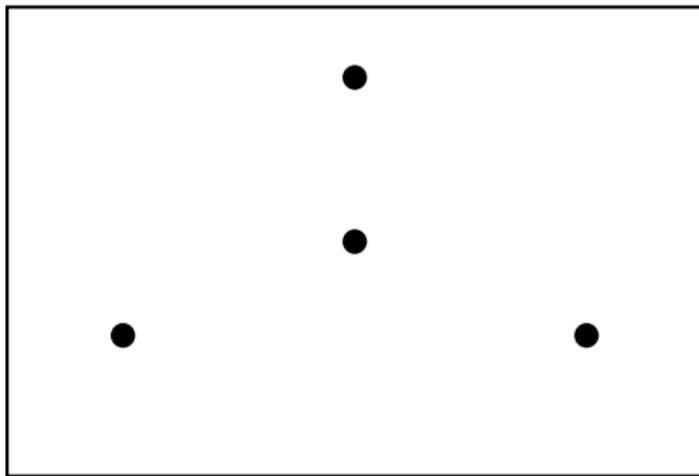
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# VC Dimension of Linear Classifiers

## Theorem

The VC dimension of the class of linear classifiers in  $\mathbb{R}^d$  is  $d + 1$

Other examples

- If  $|\mathcal{H}| < \infty$ ,  $VC(\mathcal{H}) \leq \log_2 |\mathcal{H}|$
- Threshold functions in  $\mathbb{R}$  have VC dimension 1
- Intervals in  $\mathbb{R}$  have VC dimension 2
- Axis-aligned rectangles in  $\mathbb{R}^2$  have VC dimension 4
- The VC dimension of neural networks with  $W$  weights is  $O(W)$

## VC and PAC Learnability

Consider binary classification with the zero-one loss

### Theorem

$\mathcal{H}$  is PAC-learnable if and only if  $\text{VC}(\mathcal{H}) < \infty$

The sample complexity is

$$n_{\epsilon, \delta} = \mathcal{O}\left(\frac{\text{VC}(\mathcal{H}) \log(1/\epsilon) + \log(1/\delta)}{\epsilon}\right)$$

## Beyond Fundamentals

The results presented here, their proofs, and more advanced results can be found in the following books:

Shai Shalev-Shwartz and Shai Ben-David (2014). *Understanding Machine Learning - From Theory to Algorithms*. Cambridge University Press

Mehryar Mohri, Afshin Rostamizadeh, and Ameet Talwalkar (2012). *Foundations of Machine Learning*. Adaptive computation and machine learning. MIT Press

# Statistical Learning Theory

*Thank you for listening!*

*Any questions?*